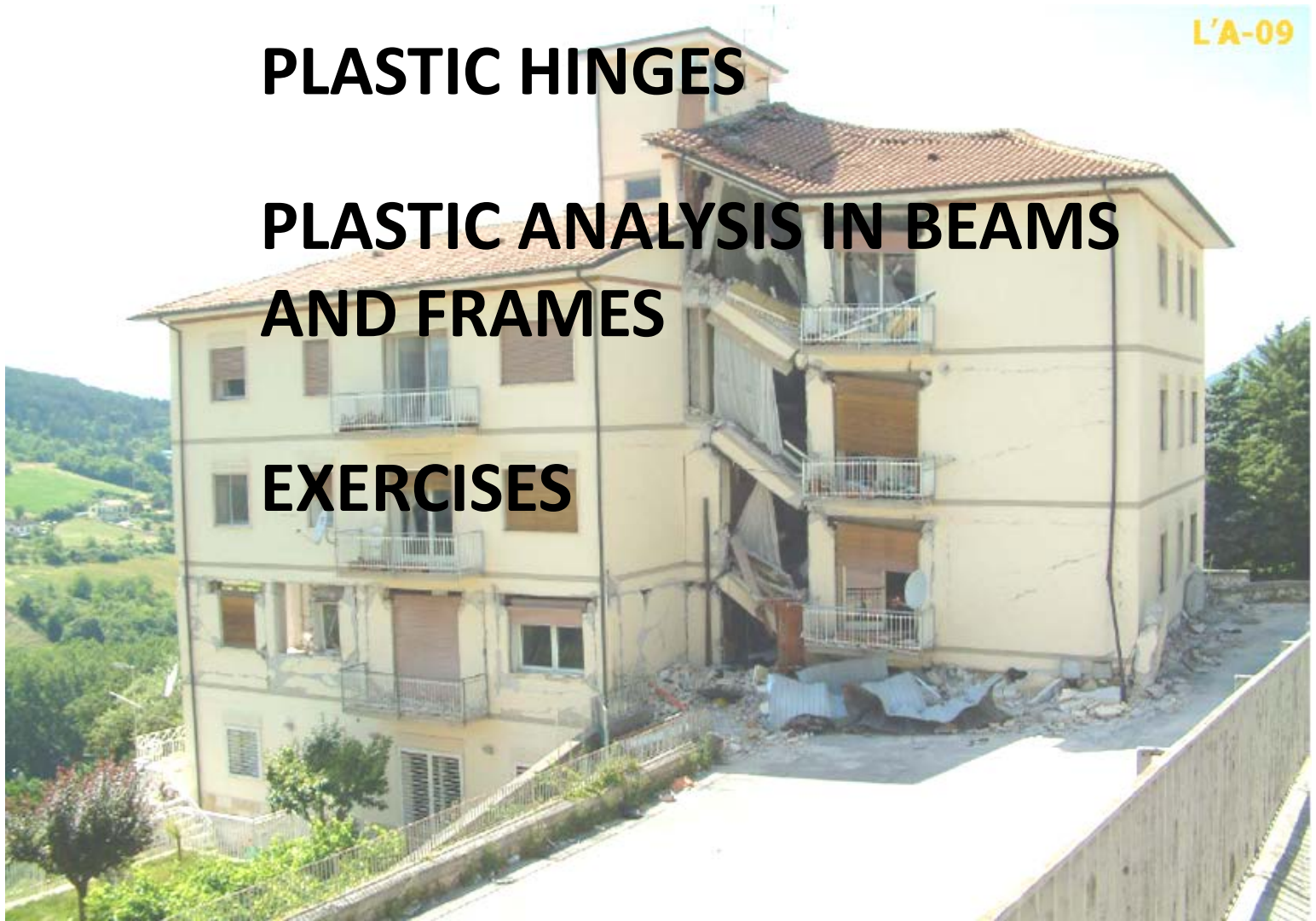
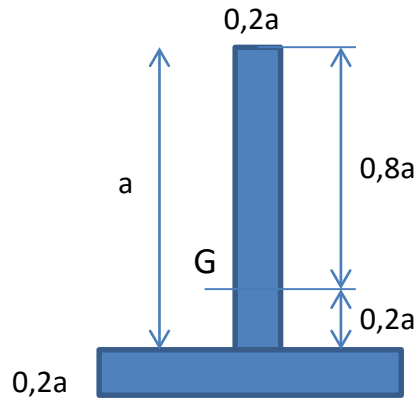


# PLASTIC HINGES

# PLASTIC ANALYSIS IN BEAMS AND FRAMES

# EXERCISES





Gravity center (Static moments)

$$a \times 0,2 a \times \left( \frac{a}{2} + 0,2 a \right) + a \times 0,2 a \times \frac{0,2 a}{2} = Y_G \times 2 \times a \times 0,2 a \quad Y_G = 0,4 a$$

Moment of Inertia (Steiner Theorem)

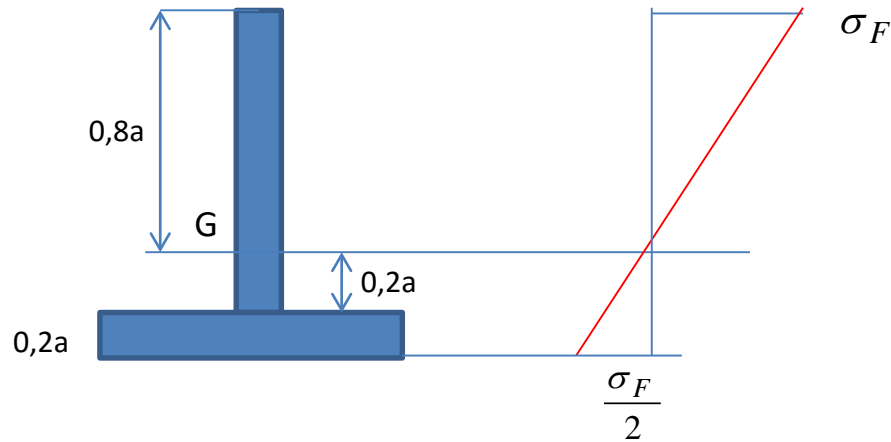
$$I = \frac{1}{12} \times 0,2 a \times a^3 + a \times 0,2 a \times (0,5 a - 0,2 a)^2 + \frac{1}{12} \times a \times (0,2 a)^3 + a \times 0,2 a \times (0,4 a - 0,1 a)^2$$

$$I = \frac{160}{3} \times 10^{-3} a^4$$





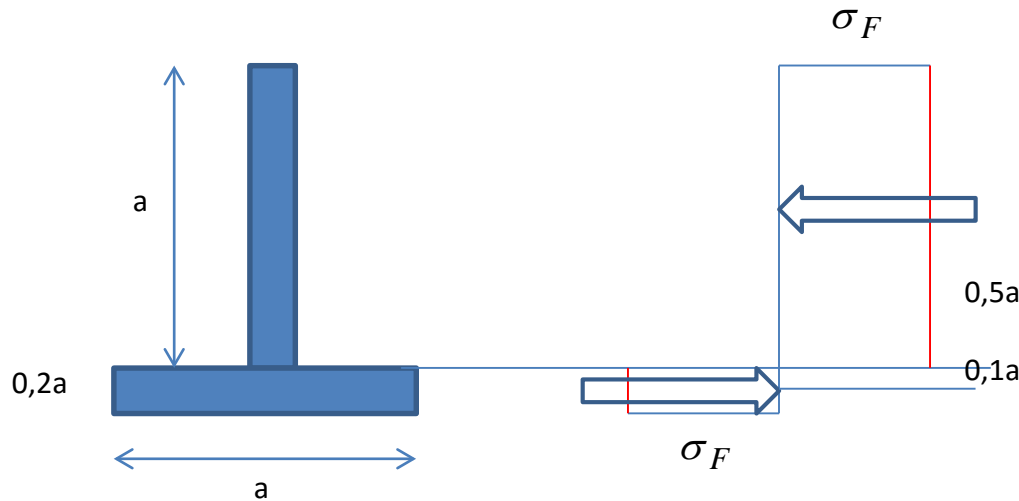
## Elastic Limit, Bending Moment



$$\sigma = \frac{M y}{I} \quad M = \frac{\sigma I}{y}$$

$$M_{le} = \frac{160 \times 10^{-3} a^4}{3 \times 0,8 a} \sigma_F = \frac{20}{3} \times 10^{-2} a^3 \sigma_F$$

## Plastic Bending Moment



$$M_{lp} = a \times 0,2 a \times 0,6 a \times \sigma_F = 1,2 \times 10^{-2} a^3 \sigma_F$$

$$f = 1,8$$

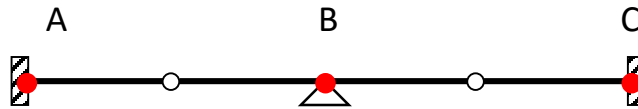


For the beam in the figure:



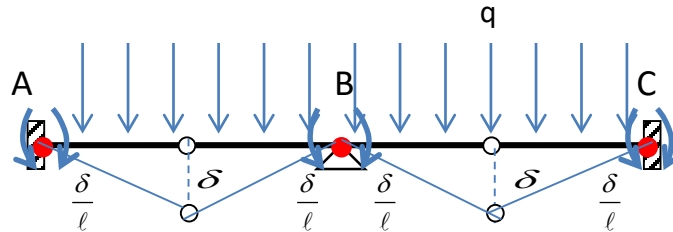
Compute the limit uniform load for a limit bending moment of value  $M$   
Calculate the static reaction forces and draw the bending moment law for  $M_f$

The beam has 2 intermediate hinges and the 4 sections are of the same length  $l$



Symmetry

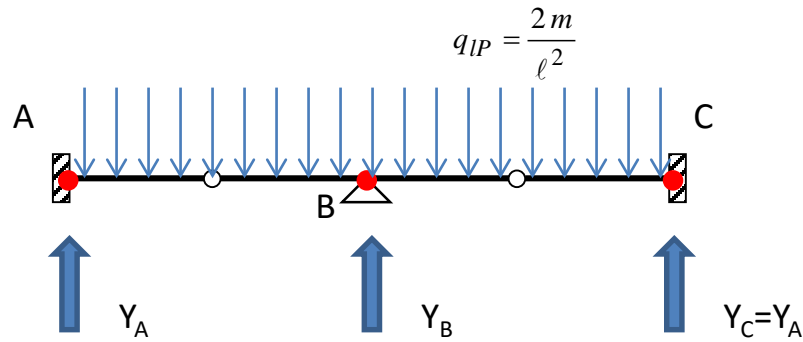
Single mechanism



$$q \times \frac{1}{2} 2l \times \delta + q \times \frac{1}{2} 2l \times \delta = -M_A \times \frac{\delta}{l} - M_B \times \left( \frac{\delta}{l} + \frac{\delta}{l} \right) - M_C \frac{\delta}{l}$$

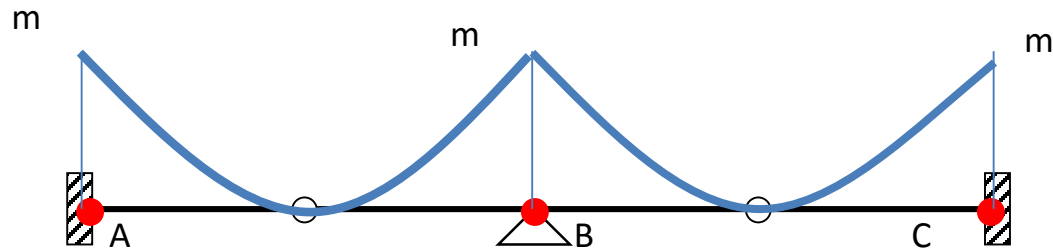
$$q_{lp} = \frac{2m}{l^2}$$

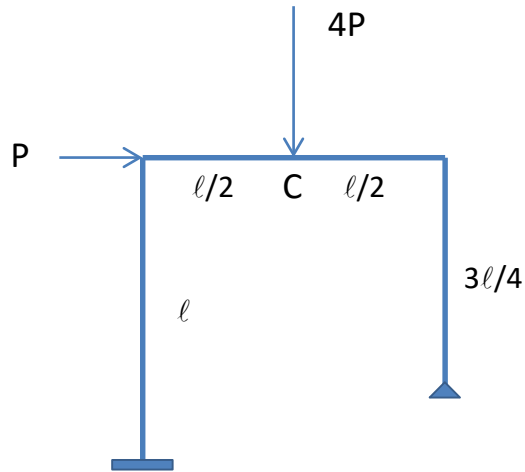




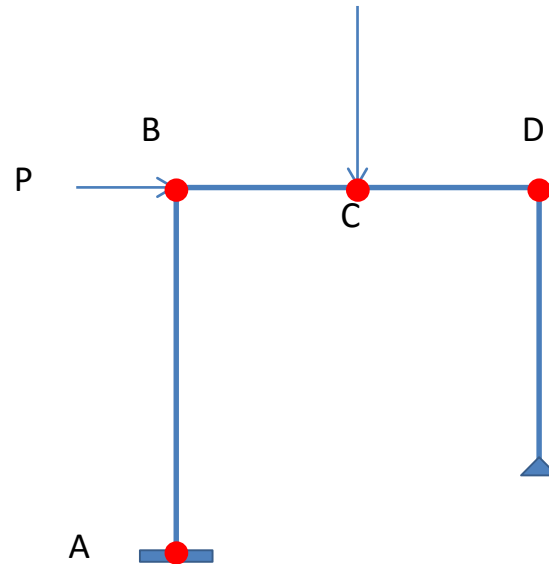
$$Y_A \times \ell - \frac{2m}{\ell^2} \times \ell \times \frac{\ell}{2} - m = 0 \quad Y_A = Y_C = \frac{2m}{\ell}$$

$$Y_B = \frac{2m}{\ell^2} \times 4\ell - 2 \times \frac{2m}{\ell} = \frac{4m}{\ell}$$

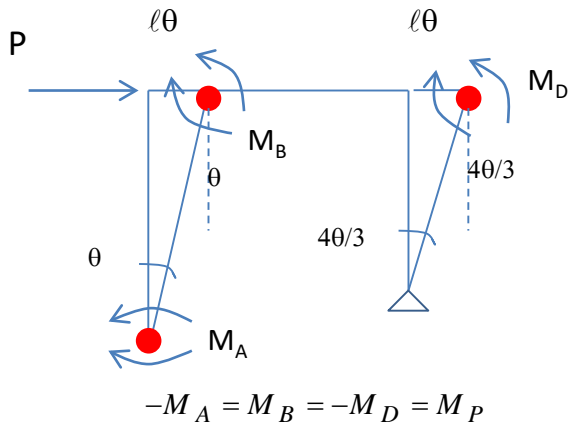




Critical Sections	A	B	C	D
Hyperstatic degree		2		
Plastic Hinges			3	
Mechanisms				4



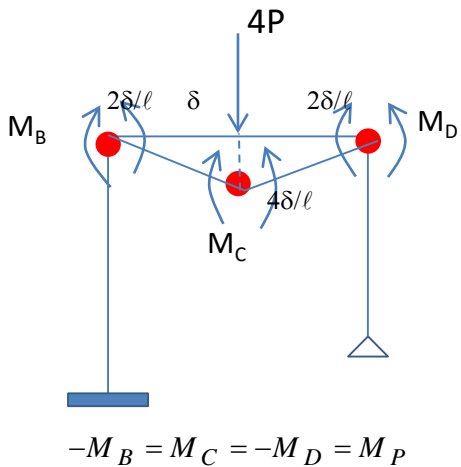
## Translational Mechanism



$$P \times \mathcal{G} \ell = -M_A \times \mathcal{G} + M_B \times \mathcal{G} - M_D \times \frac{4\mathcal{G}}{3}$$

$$P \ell = \frac{10 M_P}{3} \quad P_{lp} = \frac{10 M_P}{3 \ell}$$

## Lintel Failure Mechanism



$$4P \times \delta = -M_B \times \frac{2\delta}{\ell} + M_C \times \left( \frac{2\delta}{\ell} + \frac{2\delta}{\ell} \right) - M_D \times \frac{2\delta}{\ell}$$

$$4P = \frac{8 M_P}{\ell} \quad P_{lp} = \frac{2 M_P}{\ell}$$

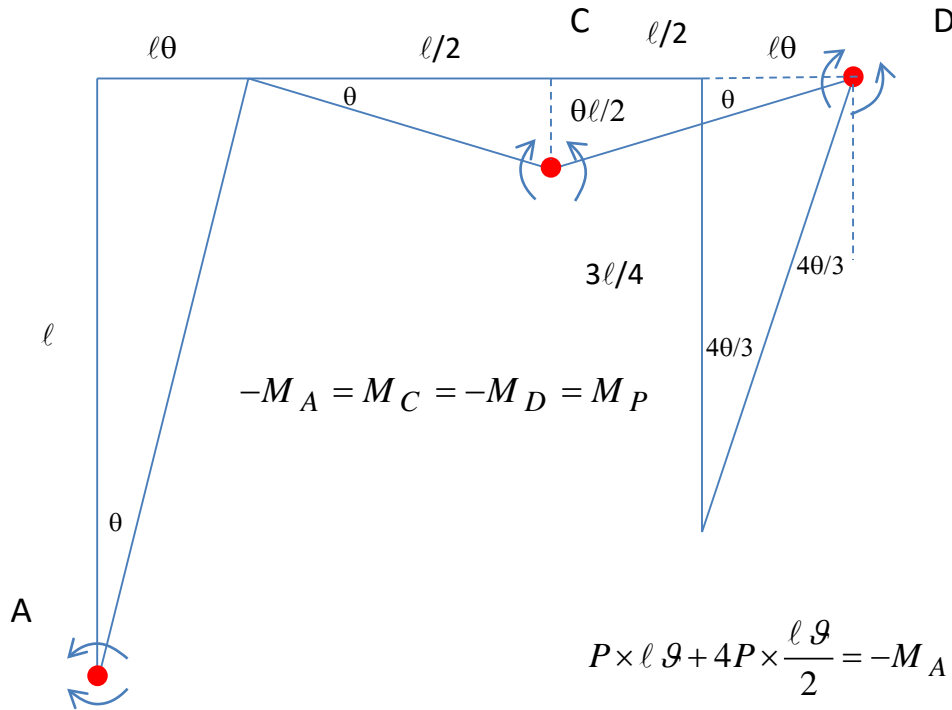




## Combination of Mechanisms

MECHANISM	A	B	C	D	$T_e \times P_l$	$T_i \times M_p/l$	$P_{lp} \times M_p/l$
ABD	-1	+1	0	-4/3	1	10/3	10/3
BCD	0	-2	4	-2	4	8	2
ACD	-2	0	4	-14/3	6	32/3	32/18 < 2
2 x ABD + BCD							

### Mechanism ACD



$$-M_A = M_C = -M_D = M_P$$

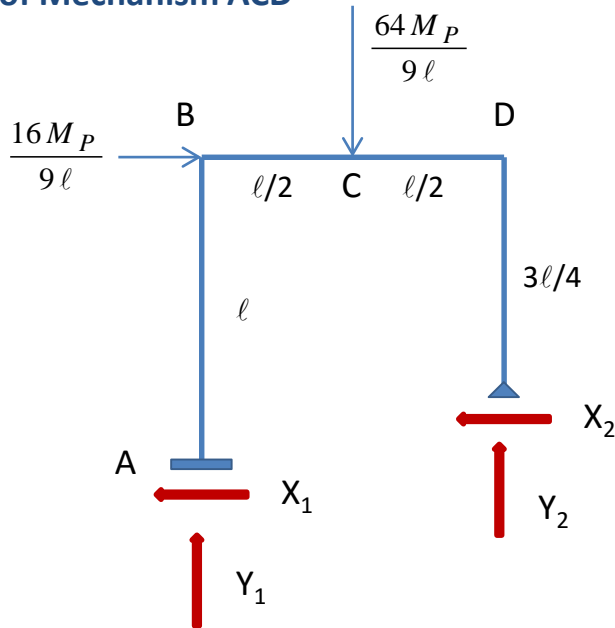
$$P \times l \vartheta + 4P \times \frac{l \vartheta}{2} = -M_A \times \vartheta + M_C \times (\vartheta + \vartheta) - M_D \times \left( \vartheta + \frac{4\vartheta}{3} \right)$$

$$3P = \frac{8M_P}{l}$$

$$P_{lp} = \frac{16M_P}{9l}$$



## Verification of Mechanism ACD



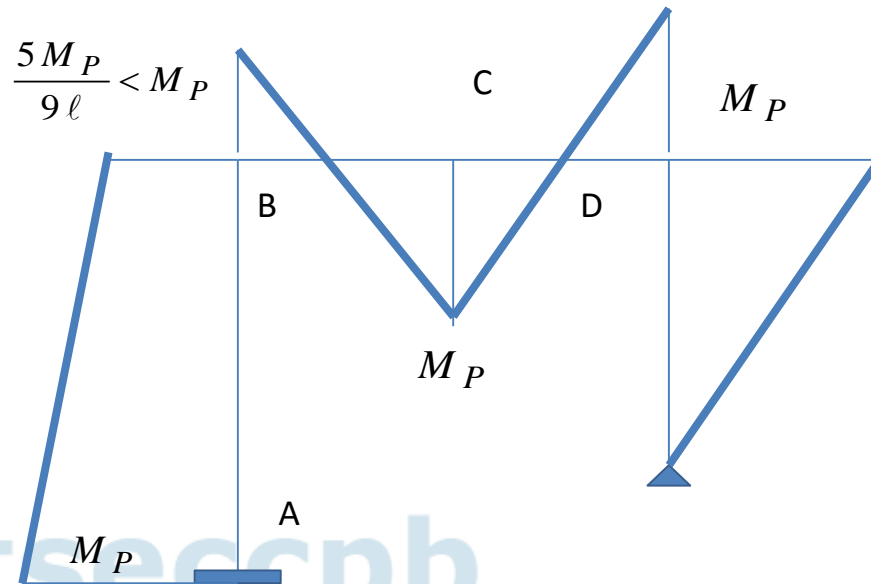
$$X_2 \times \frac{3l}{4} = M_P \quad X_2 = \frac{4M_P}{3l}$$

$$X_1 = \frac{16M_P}{9l} - \frac{4M_P}{3l} = \frac{4M_P}{9l}$$

$$Y_2 \times \frac{l}{2} - M_P = M_P \quad Y_2 = \frac{4M_P}{l}$$

$$Y_1 = \frac{64M_P}{9l} - \frac{4M_P}{l} = \frac{28M_P}{9l}$$

$$M_B = X_1 \times l - \frac{4M_P}{9l} - M_P = -\frac{5M_P}{9l} < -M_P$$

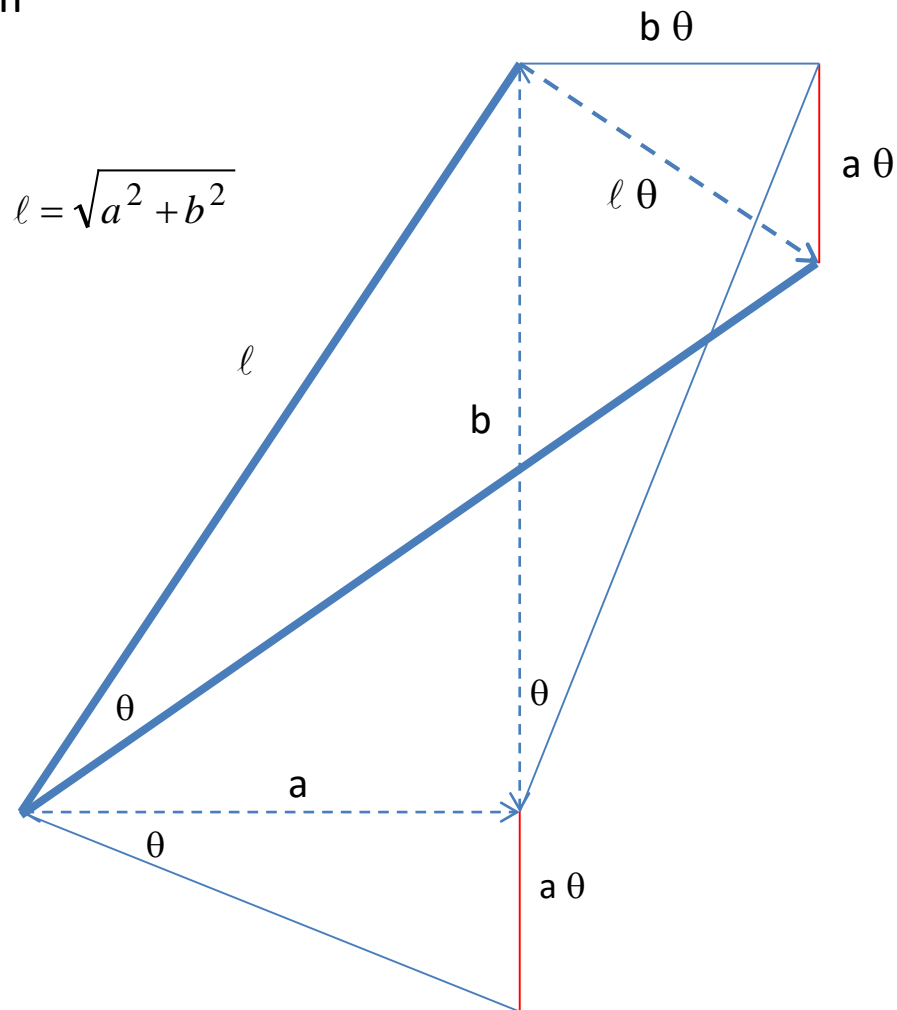


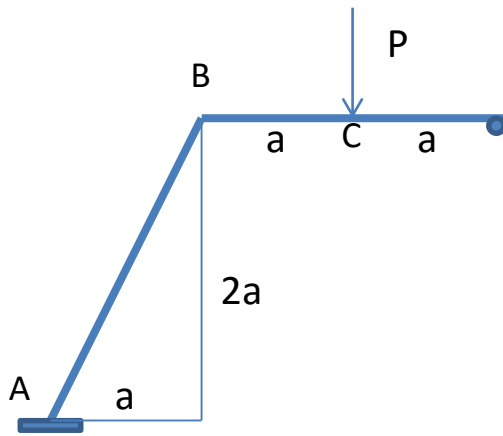
**The  $M_p$  is not exceeded**

$$P_{lp} = \frac{16M_P}{9l}$$

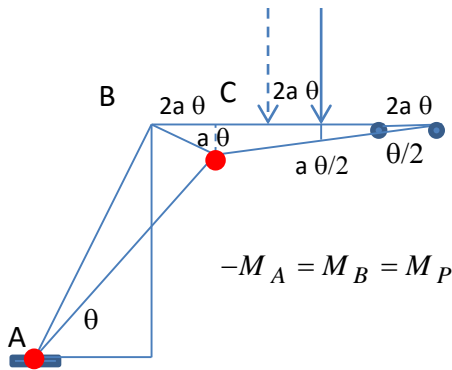


# Movement of the leaning beam





Critical Sections	A	B	C
Hyperstatic degree		1	
Plastic Hinges		2	
Mechanisms		3	

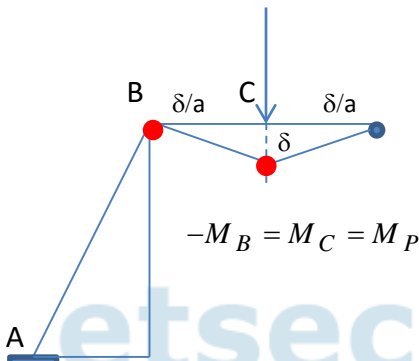


### Translational Mechanism

$$P \times a \frac{\vartheta}{2} = -M_A \times \vartheta + M_B \times \left( \vartheta + \frac{\vartheta}{2} \right)$$

$$P a = -2 M_A + 3 M_B \quad P_{lp} = \frac{5 M_P}{a}$$

### Lintel Failure Mechanism



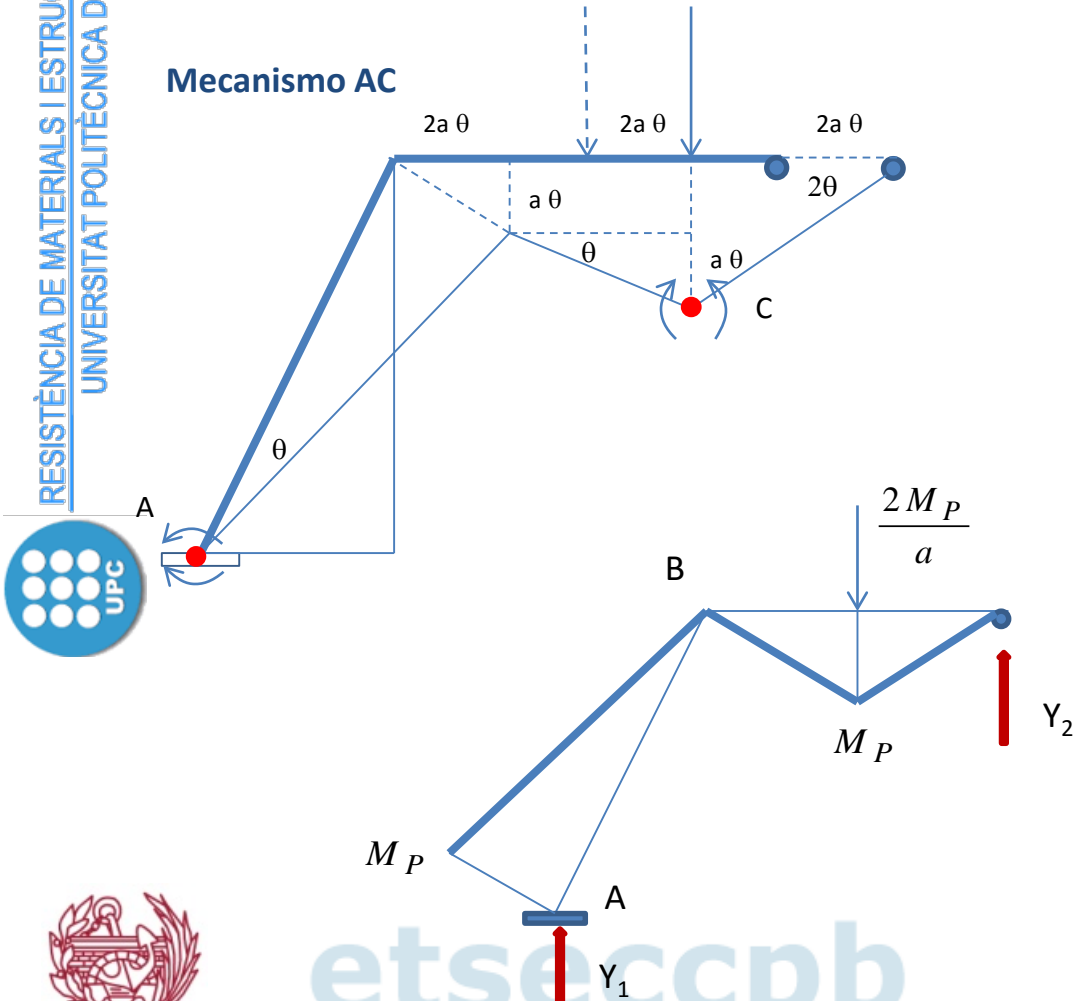
$$P \times \delta = -M_B \times \frac{\delta}{a} + M_C \times \left( \frac{\delta}{a} + \frac{\delta}{a} \right)$$

$$P a = -M_B + 2 M_C \quad P_{lp} = \frac{3 M_P}{a}$$

## Mechanism Combination

MECHANISM	A	B	C	$T_e \times P a$	$T_i \times M_p/a$	$P_{lp} \times M_p/a$
AB	-2	3	0	1	5	5
BC	0	-1	2	1	3	3
AC	-2	0	6	4	8	2
ABD + 3 x BC						

Mecanismo AC



$$P \times 2 a \vartheta = -M_A \times \vartheta + M_C \times (\vartheta + 2 \vartheta)$$

$$P \times 2 a = -M_A + 3 M_C \quad P_{lp} = \frac{2 M_P}{a}$$

Verification of Mechanism AC

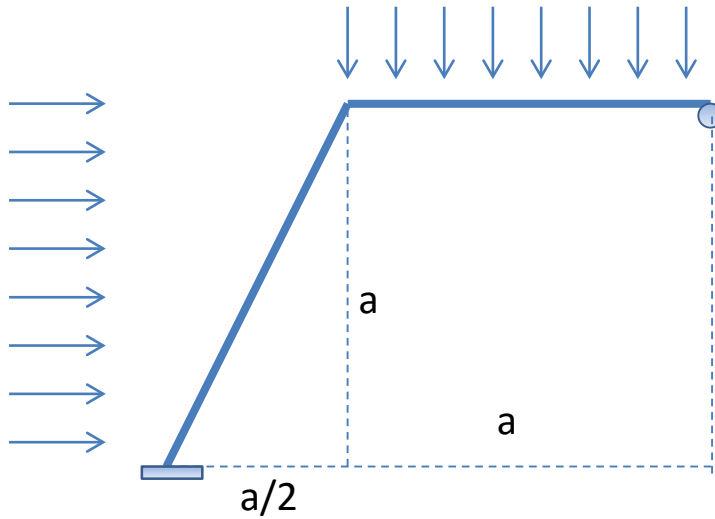
$$Y_2 \times a = M_P \quad Y_2 = \frac{M_P}{a} \quad Y_1 = \frac{M_P}{a}$$

$$M_B = Y_2 \times 2a - \frac{2 M_P}{a} \times a = 0 < M_P$$

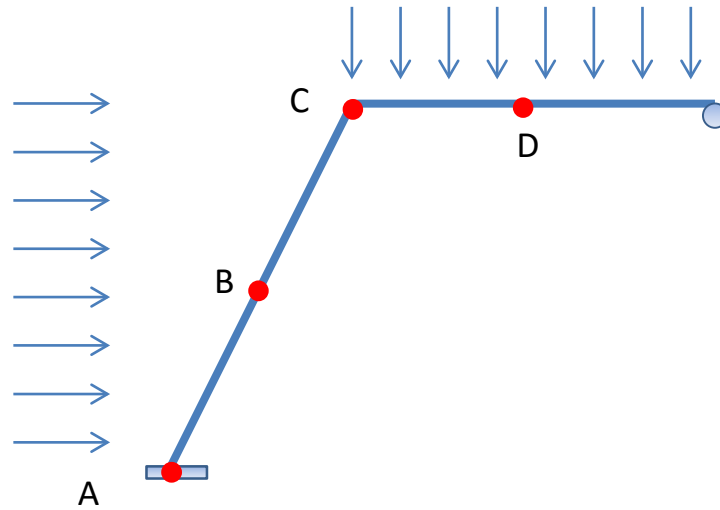
$$M_B = Y_1 \times a - M_P = 0 < M_P$$

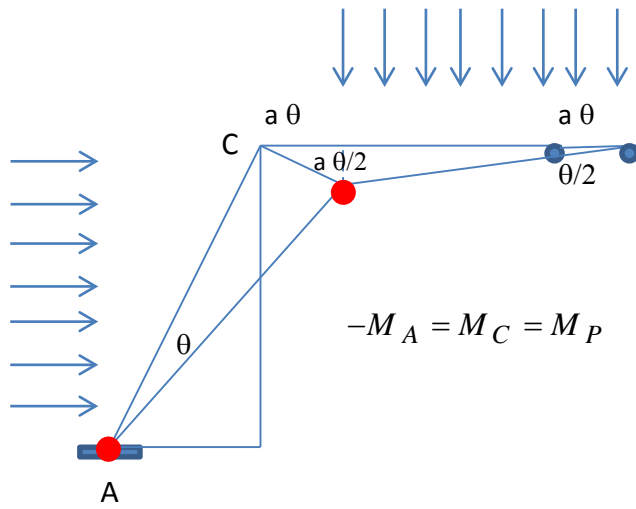
**$M_p$  is not exceeded**





Critical Sections	4
Hyperstatic Degree	1
Plastic Hinges	2
Mechanisms	3



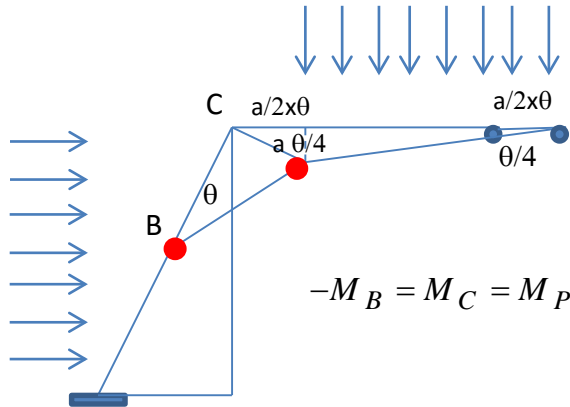


## Translational Mechanism

$$q \times \frac{1}{2} a \times a \vartheta + q \frac{1}{2} a \times a \frac{\vartheta}{2} = -M_A \times \vartheta + M_C \times \left( \vartheta + \frac{\vartheta}{2} \right)$$

$$3q \times a^2 = -4M_A + 6M_C \quad q_{lp} = \frac{10M_P}{3a^2}$$

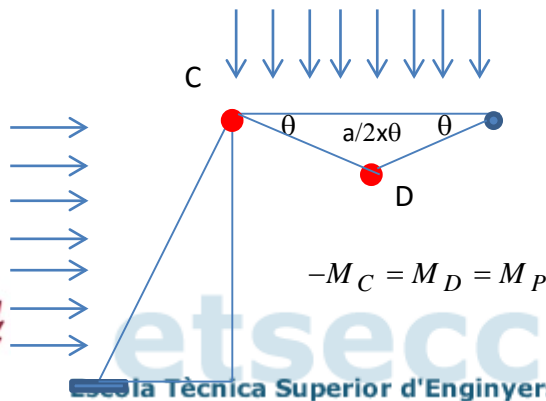
## Pillar failure mechanism



$$q \times \frac{1}{2} \frac{a}{2} \times \frac{a}{2} \vartheta + q \frac{1}{2} a \times a \frac{\vartheta}{4} = -M_B \times \vartheta + M_C \times \left( \vartheta + \frac{\vartheta}{2} \right)$$

$$q \times a^2 = -4M_B + 6M_C \quad q_{lp} = \frac{10M_P}{a^2}$$

## Lintel Failure Mechanism

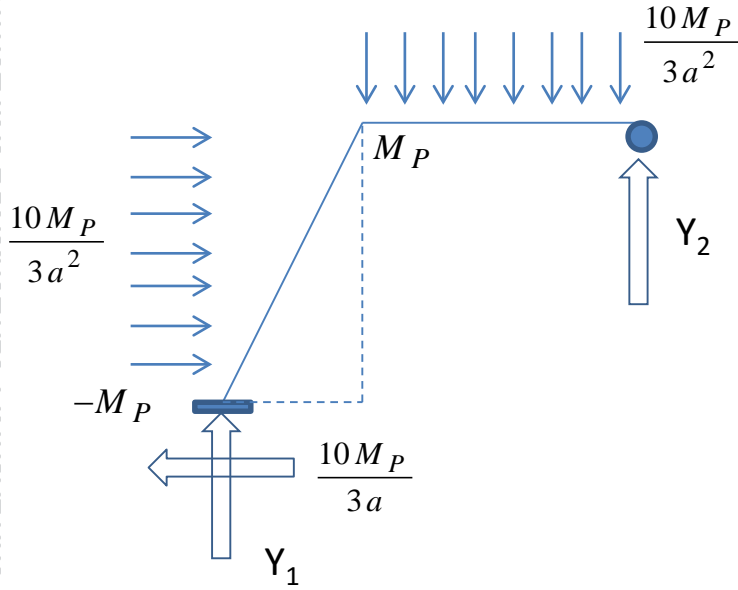


$$q \times \frac{1}{2} a \times \frac{a}{2} \vartheta = -M_C \times \vartheta + M_D \times (\vartheta + \vartheta)$$

$$q \times a^2 = -4M_C + 8M_D \quad q_{lp} = \frac{12M_P}{a^2}$$



## Verification of Mechanism AC



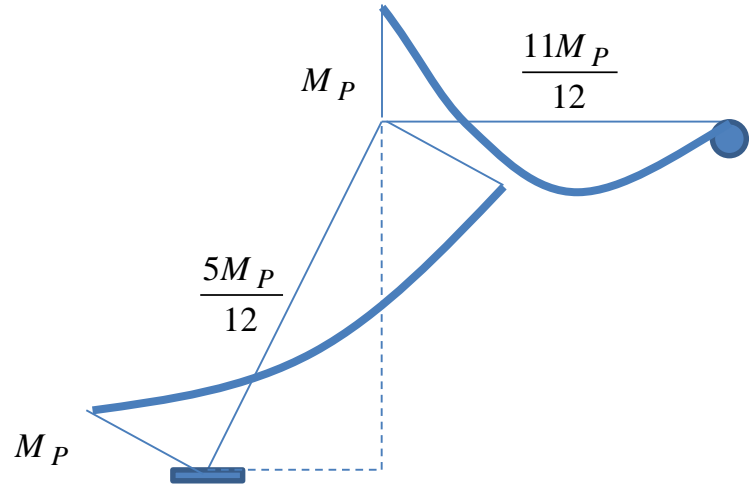
$$Y_2 \times a - \frac{10 M_P}{3 a^2} \times a \times \frac{a}{2} = M_P$$

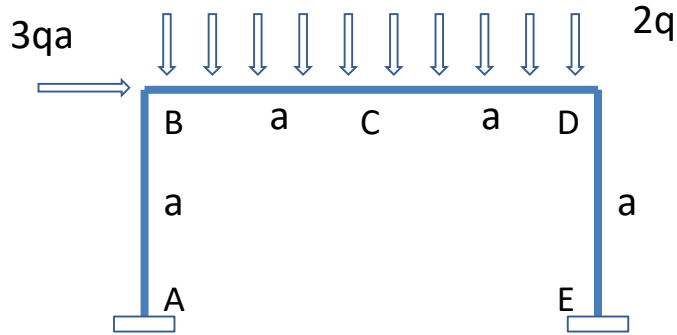
$$Y_2 = \frac{8 M_P}{3 a} \quad Y_1 = \frac{2 M_P}{3 a}$$

$$M_D = \frac{8 M_P}{3 a} \times \frac{a}{2} - \frac{10 M_P}{3 a} \times \frac{a}{2} \times \frac{a}{4} = \frac{11}{12} M_P < M_P$$

$$M_B = \frac{10 M_P}{3 a} \times \frac{a}{2} + \frac{2 M_P}{3 a} \times \frac{a}{4} - \frac{10 M_P}{3 a^2} \times \frac{a}{2} \times \frac{a}{4} - M_P = \frac{5 M_P}{12} < M_P$$

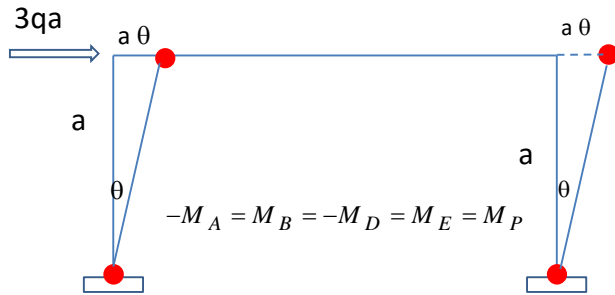
**M<sub>p</sub> is not exceeded**





Critical Sections	A	B	C	D	E
Hyperstatic degree	3				
Plastic Hinges	4				
Mechanism	3				

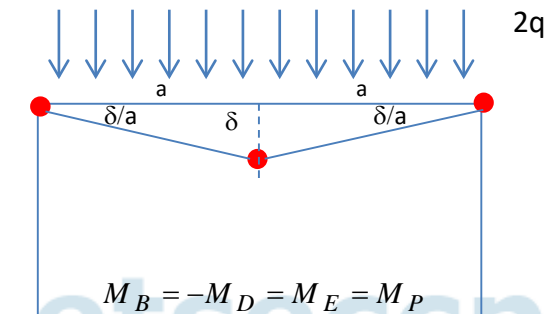
### Translational Mechanism



$$3qa \times a\vartheta = -M_A \times \vartheta + M_B \times \vartheta - M_D \times \vartheta + M_E \times \vartheta$$

$$3qa^2 = -M_A + M_B - M_D + M_E \quad q_{lp} = \frac{4M_P}{3a^2}$$

### Lintel Failure Mechanism



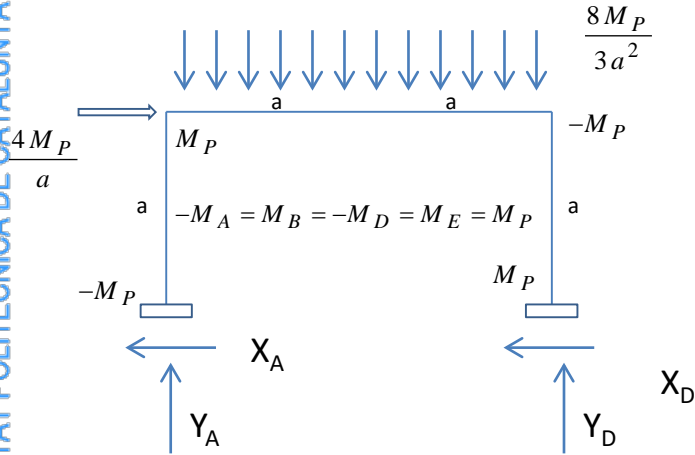
$$2q \frac{1}{2} 2a \times \delta = -M_B \times \frac{\delta}{a} + M_C \times \left( \frac{\delta}{a} + \frac{\delta}{a} \right) - M_D \times \frac{\delta}{a}$$

$$2qa^2 = -M_B + 2M_C - M_D \quad q_{lp} = \frac{2M_P}{a^2}$$





## Verification of Mechanism ABDE



$$-X_D \times a + M_P = -M_P \quad X_D = \frac{2M_P}{a} \quad X_A = \frac{2M_P}{a}$$

$$Y_D \times 2a - \frac{2M_P}{a} \times a + M_P - \frac{8M_P}{3a^2} \times 2a \times a = M_P$$

$$Y_D = \frac{11M_P}{3a} \quad Y_A = \frac{8M_P}{3a^2} \times 2a - \frac{11M_P}{3a} = \frac{5M_P}{3a}$$

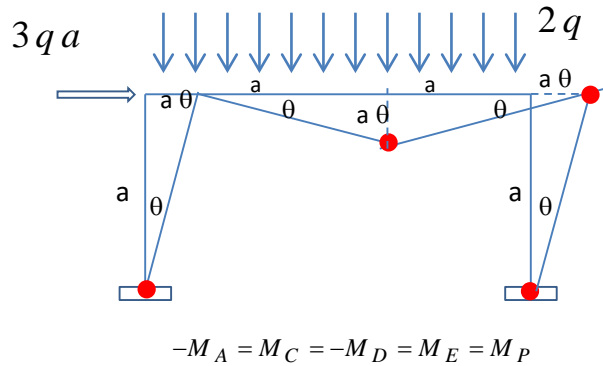
$$M_C = \frac{11M_P}{3a} \times 2a - \frac{2M_P}{a} \times a + M_P - \frac{8M_P}{3a^2} \times a \times \frac{a}{2} = 5M_P > M_P$$

**M<sub>p</sub> is exceeded**

## Verification of Mechanisms

MECHANISM	A	B	C	D	E	T <sub>e</sub> × qa <sup>2</sup>	T <sub>i</sub> × M <sub>p</sub> /l	P <sub>lp</sub> × M <sub>p</sub> /a <sup>2</sup>
ABDE	-1	+1	0	-1	+1	3	4	1,33
BCD	0	-1	2	-1	0	2	4	2
ACDE	-1	0	2	-2	+1	5	6	1,2
ABDE + BCD								



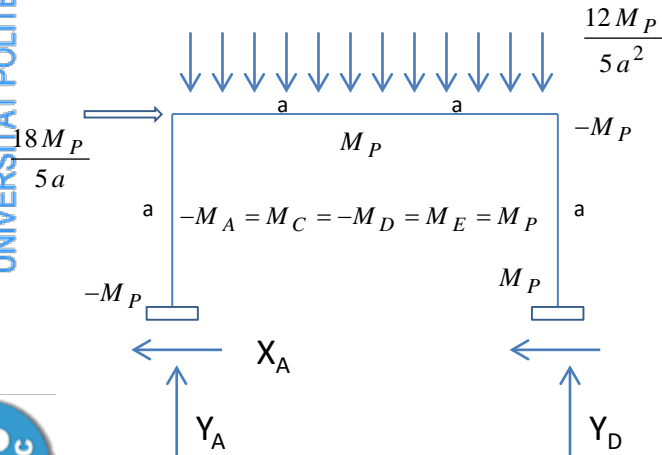


$$3qa \times a \vartheta + 2q \times \frac{1}{2} \times 2a \times a \vartheta = -M_A \times \vartheta + M_C \times (\vartheta + \vartheta) - M_D \times (\vartheta + \vartheta) + M_E \times \vartheta$$

$$5qa^2 = -M_A + 2M_B - 2M_C + M_D$$

$$q_{lp} = \frac{6M_P}{5a^2} < \frac{4M_P}{3a^2} < \frac{2M_P}{a^2}$$

### Verification of Mechanism ACDE



$$-X_D \times a + M_P = -M_P$$

$$X_D = \frac{2M_P}{a}$$

$$X_A = \frac{8M_P}{5a}$$

$$M_B = \frac{8M_P}{5a} \times a - M_P = \frac{3M_P}{5a} < M_P$$

**$M_p$  is not exceeded**

